
Applied Nonlinear Control Solution

Nonlinear Control Systems

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Operator-Based Nonlinear Control Systems

Nonlinear Control

Robust Nonlinear Control Of Industrial Evaporation Systems: Implementation Of Differential Geometric Techniques

Stabilization and Regulation of Nonlinear Systems

Nonlinear Controllability and Optimal Control

New Trends in Nonlinear Dynamics and Control, and their Applications

Local Stabilizability of Nonlinear Control Systems

Robust Control of Linear Systems and Nonlinear Control

Generalized Sylvester Equations

Nonlinear Dynamical Control Systems

Nonlinear Control Systems Design 1992

Nonlinear Control Systems Design 1995

Advances in Applied Nonlinear Optimal Control

Journal of Applied Nonlinear Dynamics

Extending H-infinity Control to Nonlinear Systems

Nonlinear Control Systems II

Applied Nonlinear Dynamics and Chaos of Mechanical Systems with Discontinuities

Analysis and Control of Nonlinear Process Systems

Nonlinear and Optimal Control Systems

Recent Trends in Applied Nonlinear Mechanics and Physics

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Nonlinear Systems Analysis

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Intelligent Interactive Multimedia Systems and Services
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Nonlinear Control Systems World Scientific Publishing
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Nonlinearities exist in all process control systems. The use of linear control techniques is valid only in a narrow region of operation. Nonlinear control is central to future industrial development. In this book, multivariable nonlinear control techniques based on differential geometry are considered in a pragmatic manner. The book provides a simplified and systematic approach to geometric nonlinear control theory. A case study of an industrial evaporator is used as an example throughout the entire book. Various other examples are also used throughout the

text to illustrate the theory. The book successfully demonstrates the superiority and simplicity of the class of controllers studied through simulations and actual plant implementations. The simulations were done using the symbolic computation package MAPLE. Discussions are given on the application of symbolic computation in process engineering. This book is aimed at industrial practitioners and postgraduates in engineering, and will be particularly valuable to practicing engineers who find the theory books on control somewhat heavy going. The insights provided in the book will encourage more industrial implementations of nonlinear controllers, and thereby help to bridge the widening gap between control theory and industrial practice.

Applied Nonlinear Control Elsevier

This book presents contributions on the most active lines of

recent advanced research in the field of nonlinear mechanics and physics selected from the 4th International Conference on Structural Nonlinear Dynamics and Diagnosis. It includes fifteen chapters by outstanding scientists, covering various aspects of applications, including road tanker dynamics and stability, simulation of abrasive wear, energy harvesting, modeling and analysis of flexoelectric nanoactuator, periodic Fermi–Pasta–Ulam problems, nonlinear stability in Hamiltonian systems, nonlinear dynamics of rotating composites, nonlinear vibrations of a shallow arch, extreme pulse dynamics in mode-locked lasers, localized structures in a photonic crystal fiber resonator, nonlinear stochastic dynamics, linearization of nonlinear resonances, treatment of a linear delay differential equation, and fractional nonlinear damping. It appeals to a wide range of experts in the field of structural nonlinear dynamics and offers researchers and engineers an introduction to the challenges posed by nonlinearities in the development of these topics

Operator-Based Nonlinear Control Systems Springer Science & Business Media

The central focus of this book is the control of continuous-time/continuous-space nonlinear systems. Using new techniques that employ the max-plus algebra, the author addresses several classes of nonlinear control problems, including nonlinear optimal control problems and nonlinear robust/H-infinity control and estimation problems. Several numerical techniques are employed, including a max-plus eigenvector approach and an approach that avoids the curse-of-dimensionality. The max-plus-based methods examined in this work belong to an entirely new class of numerical methods for the solution of nonlinear control

problems and their associated Hamilton–Jacobi–Bellman (HJB) PDEs; these methods are not equivalent to either of the more commonly used finite element or characteristic approaches. Max-Plus Methods for Nonlinear Control and Estimation will be of interest to applied mathematicians, engineers, and graduate students interested in the control of nonlinear systems through the implementation of recently developed numerical methods.

Springer

In the last two decades, the development of specific methodologies for the control of systems described by nonlinear mathematical models has attracted an ever increasing interest. New breakthroughs have occurred which have aided the design of nonlinear control systems. However there are still limitations which must be understood, some of which were addressed at the IFAC Symposium in Capri. The emphasis was on the methodological developments, although a number of the papers were concerned with the presentation of applications of nonlinear design philosophies to actual control problems in chemical, electrical and mechanical engineering.

Nonlinear Control Springer Science & Business Media

Nonlinear systems analysis - Phase plane analysis - Fundamentals of Lyapunov theory - Advanced stability theory - Describing function analysis - Nonlinear control systems design - Feedback linearization - Sliding control - Adaptive control - Control of multi-input physical systems.

Robust Nonlinear Control Of Industrial Evaporation Systems: Implementation Of Differential Geometric Techniques Springer Science & Business Media

Applied Nonlinear Control Pearson Education

Stabilization and Regulation of Nonlinear Systems CRC Press

The purpose of this book is to present a self-contained description of the fundamentals of the theory of nonlinear control systems, with special emphasis on the differential geometric approach. The book is intended as a graduate text as well as a reference to scientists and engineers involved in the analysis and design of feedback systems. The first version of this book was written in 1983, while I was teaching at the Department of Systems Science and Mathematics at Washington University in St. Louis. This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana-Champaign in 1987, at the Carl-Cranz Gesellschaft in Oberpfaffenhofen in 1987, at the University of California in Berkeley in 1988. In addition to a major rearrangement of the last two Chapters of the first version, this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985.

Nonlinear Controllability and Optimal Control Springer Science & Business Media

"Control of nonlinear systems is a multidisciplinary field involving electrical engineering, computer science, and control engineering. This book develops a systematic methodology to understand a quantitative stability result, which is an important contributor to nonlinear control systems' stability and performance. It focuses on the operator-theoretic approach, providing examples on how to apply it to network controlled systems. Current research results and the future of the operator-theoretic approach are also examined. Control theory engineers and applied mathematicians will find this work especially

rewarding"--

New Trends in Nonlinear Dynamics and Control, and their Applications Wiley-IEEE Press

This volume discusses advances in applied nonlinear optimal control, comprising both theoretical analysis of the developed control methods and case studies about their use in robotics, mechatronics, electric power generation, power electronics, micro-electronics, biological systems, biomedical systems, financial systems and industrial production processes. The advantages of the nonlinear optimal control approaches which are developed here are that, by applying approximate linearization of the controlled systems' state-space description, one can avoid the elaborated state variables transformations (diffeomorphisms) which are required by global linearization-based control methods. The book also applies the control input directly to the power unit of the controlled systems and not on an equivalent linearized description, thus avoiding the inverse transformations met in global linearization-based control methods and the potential appearance of singularity problems. The method adopted here also retains the known advantages of optimal control, that is, the best trade-off between accurate tracking of reference setpoints and moderate variations of the control inputs. The book's findings on nonlinear optimal control are a substantial contribution to the areas of nonlinear control and complex dynamical systems, and will find use in several research and engineering disciplines and in practical applications.

Local Stabilizability of Nonlinear Control Systems BoD - Books on Demand

Following the recent developments in the field of absolute

stability, Prof. Xiaoxin Liao, in conjunction with Prof. Pei Yu, has created a second edition of his seminal work on the subject. Liao begins with an introduction to the Lurie problem and Lurie control system, before moving on to the simple algebraic sufficient conditions for the absolute stability of autonomous and non-autonomous ODE systems, as well as several special classes of Lurie-type systems. The focus of the book then shifts toward the new results and research that have appeared in the decade since the first edition was published. This book is aimed to be used by undergraduates in the areas of applied mathematics, nonlinear control systems, and chaos control and synchronisation, but may also be useful as a reference for researchers and engineers. The book is self-contained, though a basic knowledge of calculus, linear system and matrix theory, and ordinary differential equations is a prerequisite.

Robust Control of Linear Systems and Nonlinear Control Elsevier
Designed for one-semester introductory senior-or graduate-level course, the authors provide the student with an introduction of analysis techniques used in the design of nonlinear and optimal feedback control systems. There is special emphasis on the fundamental topics of stability, controllability, and optimality, and on the corresponding geometry associated with these topics. Each chapter contains several examples and a variety of exercises.

Generalized Sylvester Equations Springer Science & Business Media

The series of IFAC Symposia on Nonlinear Control Systems provides the ideal forum for leading researchers and practitioners who work in the field to discuss and evaluate the latest research

and developments. This publication contains the papers presented at the 3rd IFAC Symposium in the series which was held in Tahoe City, California, USA.

Nonlinear Dynamical Control Systems Springer Science & Business Media

Control of nonlinear systems, one of the most active research areas in control theory, has always been a domain of natural convergence of research interests in applied mathematics and control engineering. The theory has developed from the early phase of its history, when the basic tool was essentially only the Lyapunov second method, to the present day, where the mathematics ranges from differential geometry, calculus of variations, ordinary and partial differential equations, functional analysis, abstract algebra and stochastic processes, while the applications to advanced engineering design span a wide variety of topics, which include nonlinear controllability and observability, optimal control, state estimation, stability and stabilization, feedback equivalence, motion planning, noninteracting control, disturbance attenuation, asymptotic tracking. The reader will find in the book methods and results which cover a wide variety of problems: starting from pure mathematics (like recent fundamental results on (non)analyticity of small balls and the distance function), through its applications to all just mentioned topics of nonlinear control, up to industrial applications of nonlinear control algorithms.

Nonlinear Control Systems Design 1992 John Wiley & Sons

This book is meant as a present to honor Professor on the occasion of his 70 birthday. It collects refereed contributions from sixty-one mathematicians from eleven countries. They cover

many different areas of research related to the work of Professor including Navier-Stokes equations, nonlinear elasticity, non-Newtonian fluids, regularity of solutions of parabolic and elliptic problems, operator theory and numerical methods. The realization of this book could not have been made possible without the generous support of Centro de Matemática Aplicada (CMA/IST) and Fundação Calouste Gulbenkian. Special thanks are due to Dr. Ulrych for the careful preparation of the final version of this book. Last but not least, we wish to express our gratitude to Dr. for her invaluable assistance from the very beginning. This project could not have been successfully concluded without her enthusiasm and loving care for her father. On behalf of the editors ADÉLIA SEQUEIRA v honored by the Order of Merit of the Czech Republic by Václav Havel, President of the Czech Republic, on the October 28, 1998, Professor Emeritus of Mathematics at the Charles University in Prague, Presidential Research Professor at the Northern Illinois University and Doctor Honoris Causa at the Technical University of Dresden, has been enriching the Czech and world mathematics with his new ideas in the areas of partial differential equations, nonlinear functional analysis and applications of the both disciplines in continuum mechanics and hydrodynamics for more than forty years.

Nonlinear Control Systems Design 1995 Springer

This outstanding reference presents current, state-of-the-art research on important problems of finite-dimensional nonlinear optimal control and controllability theory. It presents an overview of a broad variety of new techniques useful in solving classical control theory problems. Written and edited by renowned mathematicians at the forefront of research in this evolving field,

Nonlinear Controllability and Optimal Control provides detailed coverage of the construction of solutions of differential inclusions by means of directionally continuous sections ... Lie algebraic conditions for local controllability... the use of the Campbell-Hausdorff series to derive properties of optimal trajectories... the Fuller phenomenon ... the theory of orbits ... and more. Containing more than 1,300 display equations, this exemplary, instructive reference is an invaluable source for mathematical researchers and applied mathematicians, electrical and electronics, aerospace, mechanical, control, systems, and computer engineers, and graduate students in these disciplines .

Advances in Applied Nonlinear Optimal Control Springer Nature Intelligent interactive multimedia systems and services will be ever more important in computer systems. Nowadays, computers are widespread and computer users range from highly qualified scientists to non-computer expert professionals. Therefore, designing dynamic personalization and adaptivity methods to store, process, transmit and retrieve information is critical for matching the technological progress with the consumer needs. This book contains the contributions presented at the eighth international KES conference on Intelligent Interactive Multimedia: Systems and Services, which took place in Sorrento, Italy, June 17-19, 2015. It contains 33 peer-reviewed scientific contributions that focus on issues ranging from intelligent image or video storage, retrieval, transmission and analysis to knowledge-based technologies, from advanced information technology architectures for video processing and transmission to advanced functionalities of information and knowledge-based services. We believe that this book will serve as a useful source

of knowledge for both academia and industry, for all those faculty members, research scientists, scholars, Ph.D. students and practitioners, who are interested in fundamental and applied facets of intelligent interactive multimedia.

Journal of Applied Nonlinear Dynamics Elsevier

The interdisciplinary journal publishes original and new research results on Applied Nonlinear Dynamics in science and engineering. The aim of the journal is to stimulate more research interest and attention for nonlinear dynamical behaviors and engineering nonlinearity for design. The manuscripts in complex dynamical systems with nonlinearity and chaos are solicited, which includes physical mechanisms of complex systems and engineering applications of nonlinear dynamics. The journal provides a place to researchers for the rapid exchange of ideas and techniques in nonlinear dynamics and engineering nonlinearity for design. No length limitations for contributions are set, but only concisely written manuscripts are published. Brief papers are published on the basis of Technical Notes. Discussions of previous published papers are welcome. Audience Physicists, Engineers, Mathematicians, Earth and Environmental Scientists involved in Nonlinear Science and Numerical Simulation. Topics of Interest Complex dynamics in engineering Nonlinear vibration and dynamics for design Nonlinear dynamical systems and control Fractional dynamics and applications Chemical dynamics and bio-systems Economical dynamics and predictions Dynamical systems synchronization Bio-mechanical systems and devices Nonlinear structural dynamics Nonlinear multi-body dynamics Multiscale wave propagation in materials Nonlinear rotor

dynamics Nonlinear waves and acoustics

Extending H-infinity Control to Nonlinear Systems John Wiley & Sons

This practical yet rigorous book provides a development of nonlinear, Lyapunov-based tools and their use in the solution of control-theoretic problems. Rich in motivating examples and new design techniques, the text balances theoretical foundations and real-world implementation.

Nonlinear Control Systems II Springer Nature

This book is written in such a way that the level of mathematical sophistication builds up from chapter to chapter. It has been reorganized into four parts: basic analysis, analysis of feedback systems, advanced analysis, and nonlinear feedback control. Updated content includes subjects which have proven useful in nonlinear control design in recent years-- new in the 3rd edition are: expanded treatment of passivity and passivity-based control; integral control, high-gain feedback, recursive methods, optimal stabilizing control, control Lyapunov functions, and observers. For use as a self-study or reference guide by engineers and applied mathematicians.

Applied Nonlinear Dynamics and Chaos of Mechanical Systems with Discontinuities Pearson Education

A unified and coherent treatment of analytical, computational and experimental techniques of nonlinear dynamics with numerous illustrative applications. Features a discourse on geometric concepts such as Poincaré maps. Discusses chaos, stability and bifurcation analysis for systems of differential and algebraic equations. Includes scores of examples to facilitate understanding.

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