Modeling And Control Link Springer

Vehicle Dynamics and Control
Bridging Rigorous Theory and Advanced Technology
Advanced Black-Box Techniques
Modeling and Simulation
Recent Advances in Model Predictive Control
Nonlinear Model Predictive Control
The Port-Hamiltonian Approach
Modeling Biological Systems:
Infectious Disease Modeling
Modeling, Control and Optimal Design
Theory and Algorithms
Basic Concepts Illustrated by Software Examples
The Mathematics of Biological Systems
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Modeling and Electronic Management of Internal Combustion Engines
Power Electronic Converters Modeling and Control
A Case Study Approach
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Modelling and Control of Dynamic Systems Using Gaussian Process Models
Dynamics of Underactuated Multibody Systems
Modeling and Identification of Linear Parameter-Varying Systems
Automatic Control, Robotics, and Information Processing
Theory, Algorithms, and Applications
System Identification, Environmental Modelling, and Control System Design
Process Modelling for Control

Design, Modeling and Control of Nanopositioning Systems
Introduction to Multicopter Design and Control
An Application-Oriented Introduction
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Modeling and Control of Antennas and Telescopes
Introduction to Discrete Event Systems
Modeling Life
Robust Control Design for Active Driver Assistance Systems
with Case Studies
Power System Optimization Modeling in GAMS
Robust Control in Power Systems
Principles and Applications
Introduction to Modeling and Control of Internal Combustion Engine Systems

CARNEY BRYAN

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Bridging Rigorous Theory and Advanced Technology Springer Science & Business Media

Nonlinear Modeling: Advanced Black-Box Techniques discusses methods on Neural nets and related model structures for nonlinear system identification; Enhanced multi-stream Kalman filter training for recurrent networks; The support vector method of function estimation; Parametric density estimation for the classification of acoustic feature vectors in speech recognition; Wavelet-based modeling of nonlinear systems; Nonlinear identification based on fuzzy models; Statistical learning in control and matrix theory; Nonlinear time-series analysis. It also contains the results of the K.U. Leuven time series prediction competition, held within the framework of an international workshop at the K.U. Leuven, Belgium in July 1998.

Advanced Black-Box Techniques Springer

Modern power electronic converters are involved in a very broad spectrum of applications: switched-mode power supplies, electrical-machine-motion-control, active power filters, distributed power generation, flexible AC transmission systems, renewable energy conversion systems and vehicular technology, among them. Power Electronics Converters Modeling and Control teaches the reader how to analyze and model the behavior of converters and so to improve their design and control. Dealing with a set of confirmed algorithms specifically developed for use with power converters, this text is in two parts: models and control methods. The first is a detailed exposition of the most usual power converter models: · switched and averaged models; · small/large-signal models; and · time/frequency models. The second focuses on three groups of control methods: · linear control approaches normally associated with power converters; · resonant controllers because of their significance in grid-connected applications; and · nonlinear control methods including feedback linearization, stabilizing, passivity-based, and variable-structure control. Extensive case-study illustration and end-of-chapter exercises reinforce the study material. Power Electronics Converters Modeling and Control addresses the needs of graduate students interested in power electronics, providing a balanced understanding of theoretical ideas coupled with pragmatic tools based on control engineering practice in the field. Academics teaching power electronics will find this an attractive course text and the practical points make the book useful for self tuition by engineers and other practitioners wishing to bring their knowledge up to date.

Modeling and Simulation Springer

This open access Brief introduces the basic principles of control theory in a concise self-study guide. It complements the classic texts by emphasizing the simple conceptual unity of the subject. A novice can quickly see how and why the different parts fit together. The concepts build slowly and naturally one after another, until the reader soon has a view of the whole. Each concept is illustrated by detailed examples and graphics. The full software code for each example is available, providing the basis for experimenting with various assumptions, learning how to write programs for control analysis, and setting the stage for future research projects. The topics focus on robustness, design trade-offs, and optimality. Most of the book develops classical linear theory. The last part of the book considers robustness with respect to nonlinearity and explicitly nonlinear extensions, as well as advanced topics such as adaptive control and model predictive control. New students, as well as scientists from other backgrounds who want a concise and easy-to-grasp coverage of control theory, will benefit from the emphasis on concepts and broad understanding of the various approaches.

Recent Advances in Model Predictive Control Springer

The increasing demands for internal combustion engines with regard to fuel consumption, emissions and driveability lead to more actuators, sensors and complex control functions. A systematic implementation of the electronic control systems requires mathematical models from basic design through simulation to calibration. The book treats physically-based as well as models based experimentally on test benches for gasoline (spark ignition) and diesel (compression ignition) engines and uses them for the design of the different control functions. The main topics are: - Development steps for engine control - Stationary and dynamic experimental modeling - Physical models of intake, combustion, mechanical system, turbocharger, exhaust, cooling, lubrication, drive train - Engine control structures, hardware, software, actuators, sensors, fuel supply, injection system, camshaft - Engine control methods, static and dynamic feedforward and feedback control, calibration and optimization, HiL, RCP, control software development - Control of gasoline engines, control of air/fuel, ignition, knock, idle, coolant, adaptive control functions - Control of diesel engines, combustion models, air flow and exhaust recirculation control, combustion-pressure-based control (HCCI), optimization of feedforward and feedback control, smoke limitation and emission control This book is an introduction to electronic engine management with many practical examples, measurements and research results. It is aimed at advanced students of electrical, mechanical, mechatronic and control engineering and at practicing engineers in the field of combustion engine and automotive engineering.

Nonlinear Model Predictive Control Springer Science & Business Media

Energy exchange is a major foundation of the dynamics of physical systems, and, hence, in the study of complex multi-domain systems, methodologies that explicitly describe the topology of energy exchanges are instrumental in structuring the modeling and the computation of the system's dynamics and its control. This book is the outcome of the European Project "Geoplex" (FP5 IST-2001-34166) that studied and extended such system modeling and control methodologies. This unique book starts from the basic concept of port-based modeling, and

extends it to port-Hamiltonian systems. This generic paradigm is applied to various physical domains, showing its power and unifying flexibility for real multi-domain systems.
The Port-Hamiltonian Approach Springer Science & Business Media
The purpose of this book is to expose undergraduate students to the use of applied mathematics and physical argument as a basis for developing an understanding of the response characteristics, from a systems viewpoint, of a broad class of dynamic physical processes. This book was developed for use in the course ECE 355, Dynamic Systems and Modeling, in the Department of Electrical and Computer Engineering at the University of Michigan, Ann Arbor. The course ECE 355 has been elected primarily by junior and senior level students in computer engineering or in electrical engineering. Occasionally a student from outside these two programs elected the course. Thus the book is written with this class of students in mind. It is assumed that the reader has previous background in mathematics through calculus, differential equations, and Laplace transforms, in elementary physics, and in elemen tary mechanics and circuits. Although these prerequisites indicate the orientation of the material, the book should be accessible and of interest to students with a much wider spectrum of experience in applied mathemati cal topics. The subject matter of the book can be considered to form an introduc tion to the theory of mathematical systems presented from a modern, as opposed to a classical, point of view. A number of physical processes are examined where the underlying systems concepts can be clearly seen and grasped. The organization of the book around case study examples has evolved as a consequence of student suggestions.
Modeling Biological Systems: Springer
This monograph opens up new horizons for engineers and researchers in academia and in industry dealing with or interested in new developments in the field of system identification and control. It emphasizes guidelines for working solutions and practical advice for their implementation rather than the theoretical background of Gaussian process (GP) models. The book demonstrates the potential of this recent development in probabilistic machine-learning methods and gives the reader an intuitive understanding of the topic. The current state of the art is treated along with possible future directions for research. Systems control design relies on mathematical models and these may be developed from measurement data. This process of system identification, when based on GP models, can play an integral part of control design in data-based control and its description as such is an essential aspect of the text. The background of GP regression is introduced first with system identification and incorporation of prior knowledge then leading into full-blown control. The book is illustrated by extensive use of examples, line drawings, and graphical presentation of computer-simulation results and plant measurements. The research results presented are applied in real-life case studies drawn from successful applications including: a gas–liquid separator control; urban-traffic signal modelling and reconstruction; and prediction of atmospheric ozone concentration. A MATLAB® toolbox, for identification and simulation of dynamic GP models is provided for download.
Infectious Disease Modeling Springer

Mechanical engineering, and engineering discipline born of the needs of the industrial revolution, is once again asked to do its substantial share in the call for industrial renewal. The general call is urgent as we face profound issues of productivity and competitiveness that require engineering solutions, among others. The Mechanical Engineering Series is a series featuring graduate texts and research monographs intended to address the need for information in contemporary areas of mechanical engineering. The series is conceived as a comprehensive one that covers a broad range of c- centrations important to mechanical engineering graduate education and research. We are fortunate to have a distinguished roster of series editors, each an expert in one of the areas of concentration. The names of the series editors are listed on page vi of this volume. The areas of concentration are applied mechanics, biomechanics, computational mechanics, dynamic systems and control, energetics, mechanics of materials, processing, thermal science, and tribology. Preface This book is based on my experience with the control systems of antennas and radiotelescopes. Overwhelmingly, it is based on experience with the NASA Deep Space Network (DSN) antennas. It includes modeling the antennas, developing control algorithms, eld testing, system identi cation, performance evaluation, and 1 troubleshooting. My previous book emphasized the theoretical aspects of antenna control engineering, while this one describes the application part of the antenna control engineering.

Modeling, Control and Optimal Design Physica

This book contains extended, in-depth presentations of the plenary talks from the 16th French-German-Polish Conference on Optimization, held in Kraków, Poland in 2013. Each chapter in this book exhibits a comprehensive look at new theoretical and/or application-oriented results in mathematical modeling, optimization, and optimal control. Students and researchers involved in image processing, partial differential inclusions, shape optimization, or optimal control theory and its applications to medical and rehabilitation technology, will find this book valuable. The first chapter by Martin Burger provides an overview of recent developments related to Bregman distances, which is an important tool in inverse problems and image processing. The chapter by Piotr Kalita studies the operator version of a first order in time partial differential inclusion and its time discretization. In the chapter by Günter Leugering, Jan Sokołowski and Antoni Żochowski, nonsmooth shape optimization problems for variational inequalities are considered. The next chapter, by Katja Mombaur is devoted to applications of optimal control and inverse optimal control in the field of medical and rehabilitation technology, in particular in human movement analysis, therapy and improvement by means of medical devices. The final chapter, by Nikolai Osmolovskii and Helmut Maurer provides a survey on no-gap second order optimality conditions in the calculus of variations and optimal control, and a discussion of their further development.

Theory and Algorithms Springer Nature

This unique textbook comprehensively introduces the field of discrete event systems, offering a breadth of coverage that makes the material accessible to readers of varied backgrounds. The book emphasizes a unified modeling framework that transcends specific application areas, linking the following topics in a coherent manner: language and automata theory,

supervisory control, Petri net theory, Markov chains and queueing theory, discrete-event simulation, and concurrent estimation techniques. Topics and features: detailed treatment of automata and language theory in the context of discrete event systems, including application to state estimation and diagnosis comprehensive coverage of centralized and decentralized supervisory control of partially-observed systems timed models, including timed automata and hybrid automata stochastic models for discrete event systems and controlled Markov chains discrete event simulation an introduction to stochastic hybrid systems sensitivity analysis and optimization of discrete event and hybrid systems new in the third edition: opacity properties, enhanced coverage of supervisory control, overview of latest software tools This proven textbook is essential to advanced-level students and researchers in a variety of disciplines where the study of discrete event systems is relevant: control, communications, computer engineering, computer science, manufacturing engineering, transportation networks, operations research, and industrial engineering. Christos G. Cassandras is Distinguished Professor of Engineering, Professor of Systems Engineering, and Professor of Electrical and Computer Engineering at Boston University. Stéphane Lafortune is Professor of Electrical Engineering and Computer Science at the University of Michigan, Ann Arbor.
Basic Concepts Illustrated by Software Examples Springer Nature
Robust Control in Power Systems deals with the applications of new techniques in linear system theory to control low frequency oscillations in power systems. The book specifically focuses on the analysis and damping of inter-area oscillations in the systems which are in the range of 0.2-1 Hz. The damping control action is injected through high power electronic devices known as flexible AC transmission system (FACTS) controllers. Three commonly used FACTS controllers: controllable series capacitors (CSCs) controllable phase shifters (CPSs) and static var compensators (SVCs) have been used in this book to control the inter-area oscillations. The overview of linear system theory from the perspective of power system control is explained through examples. The damping control design is formulated as norm optimization problem. The H_infinity, H2 norm of properly defined transfer functions are minimized in linear matrix inequalities (LMI) framework to obtain desired performance and stability robustness. Both centralized and decentralized control structures are used. Usually the transmission of feedback signal from a remote location encounters delays making it difficult to control the system. Smith predictor based approach has been successfully explored in this book as a solution to such a problem. Robust Control in Power Systems will be valuable to academicians in the areas of power, control and system theory, as well as professionals in the power industry.
Springer Science & Business Media
Model-Based Control will be a collection of state-of-the-art contributions in the field of modelling, identification, robust control and optimization of dynamical systems, with particular attention to the application domains of motion control systems (high-accuracy positioning systems) and large scale industrial process control systems.The book will be directed to academic and industrial people involved in research in systems and control, industrial process control and mechatronics.
The Mathematics of Biological Systems Springer Science &

Business Media
This innovative textbook brings together modern concepts in mathematical epidemiology, computational modeling, physics-based simulation, data science, and machine learning to understand one of the most significant problems of our current time, the outbreak dynamics and outbreak control of COVID-19. It teaches the relevant tools to model and simulate nonlinear dynamic systems in view of a global pandemic that is acutely relevant to human health. If you are a student, educator, basic scientist, or medical researcher in the natural or social sciences, or someone passionate about big data and human health: This book is for you! It serves as a textbook for undergraduates and graduate students, and a monograph for researchers and scientists. It can be used in the mathematical life sciences suitable for courses in applied mathematics, biomedical engineering, biostatistics, computer science, data science, epidemiology, health sciences, machine learning, mathematical biology, numerical methods, and probabilistic programming. This book is a personal reflection on the role of data-driven modeling during the COVID-19 pandemic, motivated by the curiosity to understand it.
Nonlinear Modeling Springer Nature
The rapid evolution of computer science, communication, and information technology has enabled the application of control techniques to systems beyond the possibilities of control theory just a decade ago. Critical infrastructures such as electricity, water, traffic and intermodal transport networks are now in the scope of control engineers. The sheer size of such large-scale systems requires the adoption of advanced distributed control approaches. Distributed model predictive control (MPC) is one of the promising control methodologies for control of such systems. This book provides a state-of-the-art overview of distributed MPC approaches, while at the same time making clear directions of research that deserve more attention. The core and rationale of 35 approaches are carefully explained. Moreover, detailed step-by-step algorithmic descriptions of each approach are provided. These features make the book a comprehensive guide both for those seeking an introduction to distributed MPC as well as for those who want to gain a deeper insight in the wide range of distributed MPC techniques available.
Control Theory Tutorial Springer Science & Business Media
This unique book describes how the General Algebraic Modeling System (GAMS) can be used to solve various power system operation and planning optimization problems. This book is the first of its kind to provide readers with a comprehensive reference that includes the solution codes for basic/advanced power system optimization problems in GAMS, a computationally efficient tool for analyzing optimization problems in power and energy systems. The book covers theoretical background as well as the application examples and test case studies. It is a suitable reference for dedicated and general audiences including power system professionals as well as researchers and developers from the energy sector and electrical power engineering community and will be helpful to undergraduate and graduate students.
Modeling and Electronic Management of Internal Combustion Engines Springer Science & Business Media
This book is dedicated to Prof. Peter Young on his 70th birthday. Professor Young has been a pioneer in systems and control, and

over the past 45 years he has influenced many developments in this field. This volume comprises a collection of contributions by leading experts in system identification, time-series analysis, environmetric modelling and control system design – modern research in topics that reflect important areas of interest in Professor Young's research career. Recent theoretical developments in and relevant applications of these areas are explored treating the various subjects broadly and in depth. The authoritative and up-to-date research presented here will be of interest to academic researcher in control and disciplines related to environmental research, particularly those to with water systems. The tutorial style in which many of the contributions are composed also makes the book suitable as a source of study material for graduate students in those areas.

Power Electronic Converters Modeling and Control Springer

Vehicle Dynamics and Control provides a comprehensive coverage of vehicle control systems and the dynamic models used in the development of these control systems. The control system applications covered in the book include cruise control, adaptive cruise control, ABS, automated lane keeping, automated highway systems, yaw stability control, engine control, passive, active and semi-active suspensions, tire-road friction coefficient estimation, rollover prevention, and hybrid electric vehicles. In developing the dynamic model for each application, an effort is made to both keep the model simple enough for control system design but at the same time rich enough to capture the essential features of the dynamics. A special effort has been made to explain the several different tire models commonly used in literature and to interpret them physically. In the second edition of the book, chapters on roll dynamics, rollover prevention and hybrid electric vehicles have been added, and the chapter on electronic stability control has been enhanced. The use of feedback control systems on automobiles is growing rapidly. This book is intended to serve as a useful resource to researchers who work on the development of such control systems, both in the automotive industry and at universities. The book can also serve as a textbook for a graduate level course on Vehicle Dynamics and Control.

A Case Study Approach Springer Science & Business Media

Internal combustion engines still have a potential for substantial improvements, particularly with regard to fuel efficiency and environmental compatibility. These goals can be achieved with help of control systems. Modeling and Control of Internal Combustion Engines (ICE) addresses these issues by offering an introduction to cost-effective model-based control system design for ICE. The primary emphasis is put on the ICE and its auxiliary devices. Mathematical models for these processes are developed in the text and selected feedforward and feedback control problems are discussed. The appendix contains a summary of the most important controller analysis and design methods, and a case study that analyzes a simplified idle-speed control problem. The book is written for students interested in the design of classical and novel ICE control systems.

A Linear-Parameter-Varying Approach Springer

In the last ten years, a true explosion of investigations into fuzzy modeling and its applications in control, diagnostics, decision making, optimization, pattern recognition, robotics, etc. has been observed. The attraction of fuzzy modeling results from its

intelligibility and the high effectiveness of the models obtained. Owing to this the modeling can be applied for the solution of problems which could not be solved till now with any known conventional methods. The book provides the reader with an advanced introduction to the problems of fuzzy modeling and to one of its most important applications: fuzzy control. It is based on the latest and most significant knowledge of the subject and can be used not only by control specialists but also by specialists working in any field requiring plant modeling, process modeling, and systems modeling, e.g. economics, business, medicine, agriculture,and meteorology.