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# Beaglebone Robotic Projects

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Learning ROS for Robotics Programming  
ROS Robotics Projects  
BeagleBone Robotic Projects - Second Edition  
BeagleBone Robotic Projects  
30 BeagleBone Black Projects for the Evil Genius  
BeagleBone Home Automation Blueprints  
BeagleBone: Creative Projects for Hobbyists  
Robots, Androids and Animatrons, Second Edition  
ESP8266 Robotics Projects  
BeagleBone Robotic Projects  
Raspberry Pi Robotic Blueprints  
Learning Robotics Using Python  
Python Robotics Projects  
Raspberry Pi Robotics Essentials  
Effective Robotics Programming with ROS - Third Edition  
Human-Computer Interaction: Concepts, Methodologies, Tools, and Applications  
Bad to the Bone  
Bad to the Bone  
Learning JavaScript Robotics  
Building Networks and Servers Using BeagleBone  
Effective Robotics Programming with ROS  
Raspberry Pi Robotic Projects

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Build a variety of awesome robots that can see, sense, move, and do a lot more using the powerful Robot Operating System About This Book Create and program cool robotic projects using powerful ROS libraries Work through concrete examples that will help you build your own robotic systems of varying complexity levels This book provides relevant and fun-filled examples so you can make your own robots that can run and work Who This Book Is For This book is for robotic enthusiasts and researchers who would like to build robot applications using ROS. If you are looking to explore advanced ROS features in your projects, then this book is for you. Basic knowledge of ROS, GNU/Linux, and programming concepts is assumed. What You Will Learn Create your own self-driving car using ROS Build an intelligent robotic application using deep learning and ROS Master 3D object recognition Control a robot using virtual reality and ROS Build your own AI chatter-bot using ROS Get to know all about the autonomous navigation of robots using ROS Understand face detection and tracking using ROS Get to grips with teleoperating robots using hand gestures Build ROS-based applications using Matlab and Android Build interactive applications using TurtleBot In Detail Robot Operating System is one of the most widely used software frameworks for robotic research and for companies to model, simulate, and prototype robots. Applying your knowledge of ROS to actual robotics is much more difficult than people realize, but this title will give you what you need to create your own robotics in no time! This book is packed with over 14 ROS robotics projects that can be prototyped

without requiring a lot of hardware. The book starts with an introduction of ROS and its installation procedure. After discussing the basics, you'll be taken through great projects, such as building a self-driving car, an autonomous mobile robot, and image recognition using deep learning and ROS. You can find ROS robotics applications for beginner, intermediate, and expert levels inside! This book will be the perfect companion for a robotics enthusiast who really wants to do something big in the field. Style and approach This book is packed with fun-filled, end-to-end projects on mobile, armed, and flying robots, and describes the ROS implementation and execution of these models.

*Raspberry Pi Robotics Essentials*

BeagleBone Robotic Projects

JavaScript Robotics is on the rise. Rick Waldron, the lead author of this book and creator of the Johnny-Five platform, is at the forefront of this movement. Johnny-Five is an open source JavaScript Arduino programming framework for robotics. This book brings together fifteen innovative programmers, each creating a unique Johnny-Five robot step-by-step, and offering tips and tricks along the way. Experience with JavaScript is a prerequisite.

### **PIC Robotics: A Beginner's Guide to Robotics Projects Using the PIC**

Micro Packt Publishing Ltd

Utilize the powerful ingredients of Raspberry Pi to bring to life your amazing robots that can act, draw, and have fun with laser tags About This Book Learn to implement a number of features offered by Raspberry Pi to build your own amazing robots Understand how to add vision and voice to your robots. This fast-paced practical guide comprises a number of creative projects to take your Raspberry Pi knowledge to

the next level Who This Book Is For This all-encompassing guide was created for anyone who is interested in expanding their knowledge in applying the peripherals of Raspberry Pi. If you have a fancy for building complex-looking robots with simple, inexpensive, and readily available hardware, then this book is ideal for you. Prior understanding of Raspberry Pi with simple mechanical systems is recommended. What You Will Learn Add sensors to your robot so that it can sense the world around it Know everything there is to know about accessing motors and servos to provide movement to the robotic platform Explore the feature of adding vision to your robot so it can “see” the world around it Refine your robot with the skill of speech recognition so that it can receive commands Polish your robot by adding speech output so it can communicate with the world around it Maximize the use of servos in Raspberry Pi to create a drawing robot Strengthen your robot by adding wireless communication skills so you can see what the robot is seeing and control it from a distance Build an unbelievable autonomous hexcopter controlled by Raspberry Pi In Detail The Raspberry Pi is a series of credit card-sized single-board computers developed in the UK by the Raspberry Pi Foundation with the intention of promoting the teaching of basic computer science in schools. The Raspberry Pi is known as a tiny computer built on a single circuit board. It runs a Linux operating system, and has connection ports for various peripherals so that it can be hooked up to sensors, motors, cameras, and more. Raspberry Pi has been hugely popular among hardware hobbyists for various projects, including robotics. This book gives you an insight into implementing

several creative projects using the peripherals provided by Raspberry Pi. To start, we'll walk through the basic robotics concepts that the world of Raspberry Pi offers us, implementing wireless communication to control your robot from a distance. Next, we demonstrate how to build a sensible and a visionary robot, maximizing the use of sensors and step controllers. After that, we focus on building a wheeled robot that can draw and play hockey. To finish with a bang, we'll build an autonomous hexcopter, that is, a flying robot controlled by Raspberry Pi. By the end of this book, you will be a maestro in applying an array of different technologies to create almost any imaginable robot. Style and approach This book is an easy-to-follow, project-based guide that throws you directly into the action of creating almost any imaginable robot through blueprints. It is full of step by step instructions and screenshots to help you build amazing robots in no time at all.

### **BeagleBone By Example** Springer Nature

Leverage the power of Python to build DIY robotic projects Key Features Design, build, and stimulate collaborative robots Build high-end robotics projects such as a customized personal Jarvis Leverage the power of Python and ROS for DIY robotic projects Book Description Robotics is a fast-growing industry. Multiple surveys state that investment in the field has increased tenfold in the last 6 years, and is set to become a \$100-billion sector by 2020. Robots are prevalent throughout all industries, and they are all set to be a part of our domestic lives. This book starts with the installation and basic steps in configuring a robotic controller. You'll then move on to setting up your

environment to use Python with the robotic controller. You'll dive deep into building simple robotic projects, such as a pet-feeding robot, and more complicated projects, such as machine learning enabled home automation system (Jarvis), vision processing based robots and a self-driven robotic vehicle using Python. By the end of this book, you'll know how to build smart robots using Python. What you will learn Get to know the basics of robotics and its functions Walk through interface components with microcontrollers Integrate robotics with the IoT environment Build projects using machine learning Implement path planning and vision processing Interface your robots with Bluetooth Who this book is for If building robots is your dream, then this book is made for you. Prior knowledge of Python would be an added advantage.

#### Learning BeagleBone Python

Programming Packt Publishing Ltd Build simple yet amazing robotics projects using ESP8266 About This Book Get familiar with ESP8266 and its features. Build Wi-Fi controlled robots using ESP8266 A project based book that will use the ESP8266 board and some of its popular variations to build robots. Who This Book Is For This book is targeted at enthusiasts who are interested in developing low-cost robotics projects using ESP8266. A basic knowledge of programming will be useful but everything you need to know is covered in the book. What You Will Learn Build a basic robot with the original ESP8266, Arduino UNO, and a motor driver board. Make a Mini Round Robot with ESP8266 HUZZAH Modify your Mini Round Robot by integrating encoders with motors Use the Zumo chassis kit to build a line-following robot by connecting

line sensors Control your Romi Robot with Wiimote Build a Mini Robot Rover chassis with a gripper and control it through Wi-Fi Make a robot that can take pictures In Detail The ESP8266 Wi-Fi module is a self-contained SOC with an integrated TCP/IP protocol stack and can give any microcontroller access to your Wi-Fi network. It has a powerful processing and storage capability and also supports application hosting and Wi-Fi networking. This book is all about robotics projects based on the original ESP8266 microcontroller board and some variants of ESP8266 boards. It starts by showing all the necessary things that you need to build your development environment with basic hardware and software components. The book uses the original ESP8266 board and some variants such as the Adafruit HUZZAH ESP8266 and the Adafruit Feather HUZZAH ESP8266 . You will learn how to use different type of chassis kits, motors, motor drivers, power supplies, distribution boards, sensors, and actuators to build robotics projects that can be controlled via Wi-Fi. In addition, you will learn how to use line sensors, the ArduiCam, Wii Remote, wheel encoders, and the Gripper kit to build more specialized robots. By the end of this book, you will have built a Wi-Fi control robot using ESP8266. Style and approach A project-based guide that will help you build exciting robotics using ESP8266.

#### **Getting Started with Electronic Projects** Packt Publishing Ltd

Whether you are a hobbyist or a professional, this book will get you fully equipped to resolve the most commonly occurring media-related challenges. If you want to expand your horizons beyond lighting an LED and push the limits of your board, this is just the book

for you. Working knowledge of BeagleBone is assumed.

*Raspberry Pi Robotics Projects* Packt Publishing Ltd

This book is for anyone who has been curious about using Arduino to create robotic projects that were previously the domain of research labs of major universities or defense departments. Some programming background is useful, but if you know how to use a PC, you can, with the aid of the step-by-step instructions in this book, construct complex robotic projects that can roll, walk, swim, or fly.

*Arduino Robotic Projects* Packt Publishing Ltd

Develop practical example projects with detailed explanations; combine the projects in a vast number of ways to create different robot designs, or work through them in sequence to discover the full capability of the BeagleBone Black. This book is for anyone who is curious about using new, low-cost hardware to create robotic projects that have previously been the domain of research labs, major universities or Defence departments. Some programming experience would be useful, but if you know how to use a personal computer, you can use this book to construct far more complex systems than you would have thought possible.

[Raspberry Pi Robotic Projects - Third Edition](#) McGraw Hill Professional  
*BeagleBone Robotic Projects* Packt Publishing Ltd

[ESP8266 Robotics Projects](#) Packt Publishing Ltd

BeagleBone Black is a low-cost, open hardware computer uniquely suited to interact with sensors and actuators directly and over the Web. Introduced in April 2013 by BeagleBoard.org, a

community of developers first established in early 2008, BeagleBone Black is used frequently to build vision-enabled robots, home automation systems, artistic lighting systems, and countless other do-it-yourself and professional projects. BeagleBone variants include the original BeagleBone and the newer BeagleBone Black, both hosting a powerful 32-bit, super-scalar ARM Cortex A8 processor capable of running numerous mobile and desktop-capable operating systems, typically variants of Linux including Debian, Android, and Ubuntu. Yet, BeagleBone is small enough to fit in a small mint tin box. The "Bone" may be used in a wide variety of projects from middle school science fair projects to senior design projects to first prototypes of very complex systems. Novice users may access the power of the Bone through the user-friendly BoneScript software, experienced through a Web browser in most major operating systems, including Microsoft Windows, Apple Mac OS X, or the Linux operating systems. Seasoned users may take full advantage of the Bone's power using the underlying Linux-based operating system, a host of feature extension boards (Capes) and a wide variety of Linux community open source libraries. This book provides an introduction to this powerful computer and has been designed for a wide variety of users including the first time novice through the seasoned embedded system design professional. The book contains background theory on system operation coupled with many well-documented, illustrative examples. Examples for novice users are centered on motivational, fun robot projects while advanced projects follow the theme of assistive technology and image-processing applications.

### BeagleBone Black Cookbook Packt Publishing Ltd

Exciting new capabilities to enable even easier DIY robotics with BeagleBone Blue  
 About This Book Build powerful robots with the all new BeagleBone Blue  
 Communicate with your robot and teach it to detect and respond to its environment Control walking, rolling, swimming, and flying robots with your iOS and Android mobile devices  
 Who This Book Is For This book is for anyone who is curious about using new, low-cost hardware to create robotic projects and have previously been the domain of research labs, major universities, or defence departments. Some programming experience would be useful, but if you know how to use a personal computer, you can use this book to construct far more complex systems than you would have thought possible.  
 What You Will Learn Power on and configure the BeagleBone Blue Get to know Simple programming techniques to enable the unique hardware capabilities of the BeagleBone Blue. Connect standard hardware to enable your projects to see, speak, hear, and move Build advanced capabilities into your projects, such as GPS and sonar sensors Build complex projects that can fly, or go under or on the water In Detail BeagleBone Blue is effectively a small, light, cheap computer in a similar vein to Raspberry Pi and Arduino. It has all of the extensibility of today's desktop machines, but without the bulk, expense, or noise. This project guide provides step-by-step instructions that enable anyone to use this new, low-cost platform in some fascinating robotics projects. By the time you are finished, your projects will be able to see, speak, listen, detect their surroundings, and move in a variety of amazing ways. The

book begins with unpacking and powering up the components. This includes guidance on what to purchase and how to connect it all successfully, and a primer on programming the BeagleBone Blue. You will add additional software functionality available from the open source community, including making the system see using a webcam, hear using a microphone, and speak using a speaker. You will then learn to use the new hardware capability of the BeagleBone Blue to make your robots move, as well as discover how to add sonar sensors to avoid or find objects. Later, you will learn to remotely control your robot through iOS and Android devices. At the end of this book, you will see how to integrate all of these functionalities to work together, before developing the most impressive robotics projects: Drone and Submarine. Style and approach Develop practical example projects with detailed explanations, combine the projects in a vast number of ways to create different robot designs, or work through them in sequence to discover the full capability of the BeagleBone Blue.

### **ROS Robotics Projects** Packt Publishing Ltd

If you want a simple guide to building complex robots, then this book is for you. You'll need some programming knowledge and experience working with mechanical systems.

### **Hands-On Robotics with JavaScript** Packt Publishing Ltd

Your one-stop guide to the Robot Operating System About This Book Model your robot on a virtual world and learn how to simulate it Create, visualize, and process Point Cloud information Easy-to-follow, practical tutorials to program your own robots  
 Who This Book Is For If you are a robotic

enthusiast who wants to learn how to build and program your own robots in an easy-to-develop, maintainable, and shareable way, this book is for you. In order to make the most of the book, you should have a C++ programming background, knowledge of GNU/Linux systems, and general skill in computer science. No previous background on ROS is required, as this book takes you from the ground up. It is also advisable to have some knowledge of version control systems, such as svn or git, which are often used by the community to share code.

**What You Will Learn**

- Install a complete ROS Hydro system
- Create ROS packages and metapackages, using and debugging them in real time
- Build, handle, and debug ROS nodes
- Design your 3D robot model and simulate it in a virtual environment within Gazebo
- Give your robots the power of sight using cameras and calibrate and perform computer vision tasks with them
- Generate and adapt the navigation stack to work with your robot
- Integrate different sensors like Range Laser, Arduino, and Kinect with your robot
- Visualize and process Point Cloud information from different sensors
- Control and plan motion of robotic arms with multiple joints using MoveIt!

In Detail

If you have ever tried building a robot, then you know how cumbersome programming everything from scratch can be. This is where ROS comes into the picture. It is a collection of tools, libraries, and conventions that simplifies the robot building process. What's more, ROS encourages collaborative robotics software development, allowing you to connect with experts in various fields to collaborate and build upon each other's work. Packed full of examples, this book will help you understand the ROS framework to help you build your own

robot applications in a simulated environment and share your knowledge with the large community supporting ROS. Starting at an introductory level, this book is a comprehensive guide to the fascinating world of robotics, covering sensor integration, modeling, simulation, computer vision, navigation algorithms, and more. You will then go on to explore concepts like topics, messages, and nodes. Next, you will learn how to make your robot see with HD cameras, or navigate obstacles with range sensors. Furthermore, thanks to the contributions of the vast ROS community, your robot will be able to navigate autonomously, and even recognize and interact with you in a matter of minutes. What's new in this updated edition? First and foremost, we are going to work with ROS Hydro this time around. You will learn how to create, visualize, and process Point Cloud information from different sensors. This edition will also show you how to control and plan motion of robotic arms with multiple joints using MoveIt! By the end of this book, you will have all the background you need to build your own robot and get started with ROS.

**Style and approach**

This book is an easy-to-follow guide that will help you find your way through the ROS framework. This book is packed with hands-on examples that will help you program your robot and give you complete solutions using ROS open source libraries and tools.

**BeagleBone: Creative Projects for Hobbyists** Packt Publishing Ltd

Over 60 recipes and solutions for inventors, makers, and budding engineers to create projects using the BeagleBone Black

**About This Book**

Learn how to develop applications with the BeagleBone Black and open source Linux software

Sharpen your expertise in

making sophisticated electronic devices. Explore the BeagleBone Black with this easy-to-succeed recipe format. Who This Book Is For If you are a hardware, Linux, and/or microcomputing novice, or someone who wants more power and possibilities with product prototypes, electronic art projects, or embedded computing experiments, then this book is for you. It is for Internet of Things enthusiasts who want to use more sophisticated hardware than the Raspberry Pi or the Arduino can provide. Whether you are an engineering student, a DIYer, an inventor, or a budding electronics enthusiast, this book delivers accessible, easy-to-succeed instructions for using an advanced microcomputing platform. What You Will Learn Set up and run the BeagleBone Black for the first time. Learn the basics of microcomputing and Linux using the command line and easy kernel mods. Make introductory projects with Python, JavaScript, BoneScript, and Node.js. Explore physical computing and simple circuits using buttons, LEDs, sensors, and motors. Discover the unique features of the BeagleBone Black and its real-time computing functions. Build intermediate level audio and video applications. Assemble and add ingredients for creating Internet of Things prototypes. In Detail There are many single-board controllers and computers such as Arduino, Udoo, or Raspberry Pi, which can be used to create electronic prototypes on circuit boards. However, when it comes to creating more advanced projects, BeagleBone Black provides a sophisticated alternative. Mastering the BeagleBone Black enables you to combine it with sensors and LEDs, add buttons, and marry it to a variety of add-on boards. You can transform this tiny device into the brain for an

embedded application or an endless variety of electronic inventions and prototypes. With dozens of how-tos, this book kicks off with the basic steps for setting up and running the BeagleBone Black for the first time, from connecting the necessary hardware and using the command line with Linux commands to installing new software and controlling your system remotely. Following these recipes, more advanced examples take you through scripting, debugging, and working with software source files, eventually working with the Linux kernel. Subsequently, you will learn how to exploit the board's real-time functions. We will then discover exciting methods for using sound and video with the system before marching forward into an exploration of recipes for building Internet of Things projects. Finally, the book finishes with a dramatic arc upward into outer space, when you explore ways to build projects for tracking and monitoring satellites. Style and approach This comprehensive recipe book deconstructs a complex, often confusing piece of technology, and transforms it to become accessible and fun with snappy, unintimidating prose, and extensive easy-to-succeed instructions. Arduino Robotic Projects Packt Publishing Ltd Design, build, and program your own remarkable robots with JavaScript and open source hardware About This Book Learn how to leverage Johnny-Five's Read, Eval, Print Loop, and Event API to write robot code with JavaScript Unlock a world of exciting possibilities by hooking your JavaScript-programmed robots up to the internet and using external data and APIs Move your project code from the Arduino Uno to a multitude of other robotics platforms Who This Book Is For If you've worked with Arduino before or



are new to electronics and would like to try writing sketches in JavaScript, then this book is for you! Basic knowledge of JavaScript and Node.js will help you get the most out of this book. What You Will Learn Familiarise yourself with Johnny-Five Read, Eval, and Print Loop (REPL) to modify and debug robotics code in real time Build robots with basic output devices to create projects that light up, make noise, and more Create projects with complex output devices, and employ the Johnny-Five API to simplify the use of components that require complex interfaces, such as I2C Make use of sensors and input devices to allow your robotics projects to survey the world around them and accept input from users Use the Sensor and Motor objects to make it much easier to move your robotics projects Learn about the Animation API that will allow you to program complex movements using timing and key frames Bring in other devices to your Johnny-Five projects, such as USB devices and remotes Connect your Johnny-Five projects to external APIs and create your own Internet of Things! In Detail There has been a rapid rise in the use of JavaScript in recent times in a variety of applications, and JavaScript robotics has seen a rise in popularity too. Johnny-Five is a framework that gives NodeBots a consistent API and platform across several hardware systems. This book walks you through basic robotics projects including the physical hardware builds and the JavaScript code for them. You'll delve into the concepts of Johnny-Five and JS robotics. You'll learn about various components such as Digital GPIO pins, PWM output pins, Sensors, servos, and motors to be used with Johnny-Five along with some advanced components such as I2C, and SPI. You will learn to

connect your Johnny-Five robots to internet services and other NodeBots to form networks. By the end of this book, you will have explored the benefits of the Johnny-Five framework and the many devices it unlocks. Style and approach This step-by-step guide to the Johnny-Five ecosystem is explained in a conversational style, packed with examples and tips. Each chapter also explores the Johnny-Five documentation to enable you to start exploring the API on your own.

BeagleBone Media Center McGraw Hill Professional

Work through a mix of amazing robotic projects using the Raspberry Pi Zero or the Raspberry Pi 3 About This Book Easy to follow instructions, yet the ones that help you build powerful robots, and exclusive coverage of mobile robots with the Pi Zero Build robots that can run, swim and fly and the cutting-edge dimension of robotics that is possible with the Raspberry Pi Zero and Pi 3 Interact with your projects wirelessly and make sci-fi possible, right in your home Who This Book Is For This book is for hobbyists and programmers who are excited about using the Raspberry Pi 3 and Raspberry Pi Zero. It is for those who are taking their first steps towards using these devices to control hardware and software and write simple programs that enable amazing projects. No programming experience is required, just a little computer and mechanical aptitude and the desire to build some interesting projects. What You Will Learn Control a variety of different DC motors Add a USB webcam to see what your robot can see Attach a projector to project information Insert USB control hardware to control a complex robot with two legs Include speech recognition so that your projects can receive

commands Add speech output to that the robot can communicate with the world around it Include wireless communication so that you can see what the robot is seeing and control the robot from a distance In Detail This book will allow you to take full advantage of Raspberry Pi Zero and Raspberry Pi 3 by building both simple and complex robotic projects. The book takes a mission-critical approach to show you how to build amazing robots and helps you decide which board to use for which type of robot. The book puts a special emphasis on designing mobile (or movable) robots using the Raspberry Pi Zero. The projects will show inexpensive, yet powerful, ways to take full advantage. It will teach you how to program Raspberry Pi, control the movement of your robot, and add features to your robots. Style and approach This fun and practical tutorial contain step-by-step instructions to get you hands-on building inexpensive projects. It contains mission-critical chapters and everything you need to know to get started.

### **Mastering BeagleBone Robotics**

Packt Publishing Ltd

Exciting new capabilities to enable even easier DIY robotics with BeagleBone Blue About This Book\* Build powerful robots with the all new BeagleBone Blue\* Communicate with your robot and teach it to detect and respond to its environment\* Control walking, rolling, swimming, and flying robots with your iOS and Android mobile devices Who This Book Is For This book is for anyone who is curious about using new, low-cost hardware to create robotic projects and have previously been the domain of research labs, major universities, or defence departments. Some programming experience would be

useful, but if you know how to use a personal computer, you can use this book to construct far more complex systems than you would have thought possible. What You Will Learn\* Power on and configure the BeagleBone Blue\* Get to know Simple programming techniques to enable the unique hardware capabilities of the BeagleBone Blue.\* Connect standard hardware to enable your projects to see, speak, hear, and move\* Build advanced capabilities into your projects, such as GPS and sonar sensors\* Build complex projects that can fly, or go under or on the water In Detail BeagleBone Blue is effectively a small, light, cheap computer in a similar vein to Raspberry Pi and Arduino. It has all of the extensibility of today's desktop machines, but without the bulk, expense, or noise. This project guide provides step-by-step instructions that enable anyone to use this new, low-cost platform in some fascinating robotics projects. By the time you are finished, your projects will be able to see, speak, listen, detect their surroundings, and move in a variety of amazing ways. The book begins with unpacking and powering up the components. This includes guidance on what to purchase and how to connect it all successfully, and a primer on programming the BeagleBone Blue. You will add additional software functionality available from the open source community, including making the system see using a webcam, hear using a microphone, and speak using a speaker. You will then learn to use the new hardware capability of the BeagleBone Blue to make your robots move, as well as discover how to add sonar sensors to avoid or find objects. Later, you will learn to remotely control your robot through iOS and Android devices. At the end of this book, you will

see how to integrate all of these functionalities to work together, before developing the most impressive robotics projects: Drone and Submarine. Style and approach Develop practical example projects with detailed explanations, combine the projects in a vast number of ways to create different robot designs, or work through them in sequence to discover the full capability of the BeagleBone Blue.

### **Learning ROS for Robotics**

**Programming** Packt Publishing Ltd  
Learn how to build physical computing systems using BeagleBone Black and Python About This Book Get to grips with the fundamentals of BeagleBone Leverage Python scripts to program BeagleBone for your requirements Build four exciting projects, from home automation to a tele-controlled robot Who This Book Is For This book is intended for hobbyists and consumers who wish to create impressive projects using BeagleBone. You must be familiar with Python programming. What You Will Learn Program on BeagleBone Black using Python Interface sensors and actuators to BeagleBone Black Build your own real-time physical computing systems Connect physical computing systems to cloud servers Build your own home automation and home security system Build your own tele-controlled robot with real-time video streaming In Detail BeagleBone is a low cost, community-supported development platform to develop a variety of electronic projects. This book will introduce you to BeagleBone and get you building fun, cool, and innovative projects with it. Start with the specifications of BeagleBone Black and its operating systems, then get to grips with the GPIOs available in BeagleBone Black. Work through four types of

exciting projects: building real-time physical computing systems, home automation, image processing for a security system, and building your own tele-controlled robot and learn the fundamentals of a variety of projects in a single book. By the end of this book, you will be able to write code for BeagleBone in order to operate hardware and impart decision-making capabilities with the help of efficient coding in Python. Style and approach This book is a step by step guide that will walk you through the fundamentals of building different projects using BeagleBone Black. Packt Publishing Ltd

As modern technologies continue to develop and evolve, the ability of users to interface with new systems becomes a paramount concern. Research into new ways for humans to make use of advanced computers and other such technologies is necessary to fully realize the potential of 21st century tools. Human-Computer Interaction: Concepts, Methodologies, Tools, and Applications gathers research on user interfaces for advanced technologies and how these interfaces can facilitate new developments in the fields of robotics, assistive technologies, and computational intelligence. This four-volume reference contains cutting-edge research for computer scientists; faculty and students of robotics, digital science, and networked communications; and clinicians invested in assistive technologies. This seminal reference work includes chapters on topics pertaining to system usability, interactive design, mobile interfaces, virtual worlds, and more.

**ROS Robotics Projects** Packt Publishing Ltd

Build exciting robotics projects such as mobile manipulators, self-driving cars,

and industrial robots powered by ROS, machine learning, and virtual reality Key Features Create and program cool robotic projects using powerful ROS libraries Build industrial robots like mobile manipulators to handle complex tasks Learn how reinforcement learning and deep learning are used with ROS Book Description Nowadays, heavy industrial robots placed in workcells are being replaced by new age robots called cobots, which don't need workcells. They are used in manufacturing, retail, banks, energy, and healthcare, among other domains. One of the major reasons for this rapid growth in the robotics market is the introduction of an open source robotics framework called the Robot Operating System (ROS). This book covers projects in the latest ROS distribution, ROS Melodic Morenia with Ubuntu Bionic (18.04). Starting with the fundamentals, this updated edition of ROS Robotics Projects introduces you to ROS-2 and helps you understand how it is different from ROS-1. You'll be able to model and build an industrial mobile manipulator in ROS and simulate it in Gazebo 9. You'll then gain insights into handling complex robot applications using state machines and working with multiple robots at a time. This ROS book also introduces you to new and popular hardware such as Nvidia's Jetson Nano, Asus Tinker Board, and Beaglebone

Black, and allows you to explore interfacing with ROS. You'll learn as you build interesting ROS projects such as self-driving cars, making use of deep learning, reinforcement learning, and other key AI concepts. By the end of the book, you'll have gained the confidence to build interesting and intricate projects with ROS. What you will learn Grasp the basics of ROS and understand ROS applications Uncover how ROS-2 is different from ROS-1 Handle complex robot tasks using state machines Communicate with multiple robots and collaborate to build apps with them Explore ROS capabilities with the latest embedded boards such as Tinker Board S and Jetson Nano Discover how machine learning and deep learning techniques are used with ROS Build a self-driving car powered by ROS Teleoperate your robot using Leap Motion and a VR headset Who this book is for If you're a student, hobbyist, professional, or anyone with a passion for learning robotics and interested in learning about algorithms, motion control, and perception capabilities from scratch, this book is for you. This book is also ideal for anyone who wants to build a new product and for researchers to make the most of what's already available to create something new and innovative in the field of robotics.

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